

UE Linear dynamical system

ECTS 3 cred

ECTS 3 credits Component UFR PhITEM (physique, ingénierie, terre, environnement, mécanique) Semester Automne

- > Teaching language(s): English
- > Open to exchange students: Yes
- > Code d'export Apogée: PAX7ECAC

Presentation

Description

In this module, we will lay the foundations for the control of linear systems in the continuous-time as well as in the discrete-time. In the continuous-time case, we will consider the time domain as well as the frequency domain. After a brief introduction, the following concepts will be addressed: transfer function, state-space representation of linear and nonlinear systems, linearization, Linear Time invariant (LTI) and Linear Time variant (LTV) systems, Input-Output stability.

Objectives

Objectives:

The purpose of this module is to lay off the bases of control for linear systems in continuous-time as well as in discrete-time case. At the end of this class the students will be familiar with the concepts of: state-space representation, linearization, time invariance, input response, transfer function of state-space systems, input-output stability. C. Prieur and M. Fiacchini will later use these concepts in their advanced control classes.





Course parts

UE Linear dynamical systems - CM/TD

Lectures (CM) & Teaching Unit (UE)

25h

Recommended prerequisites

Laplace Transform, Bode plot, block diagram representation, Vector and matrix operations, P/PI/PID control.

Useful info

Campus

> Grenoble - Scientific Polygon

